

Preferred citation style

Axhausen, K.W. (2008) Patterns of daily movement: An agent-based model of Switzerland, presentation at the CCSS *International Workshop on Challenges and Visions in the Social Sciences 2008*, Zürich, August 2008.

Patterns of daily movement: An agent-based model of Switzerland

KW Axhausen

August 2008

 Institut für Verkehrsplanung und Transportsysteme
Institute for Transport Planning and Systems

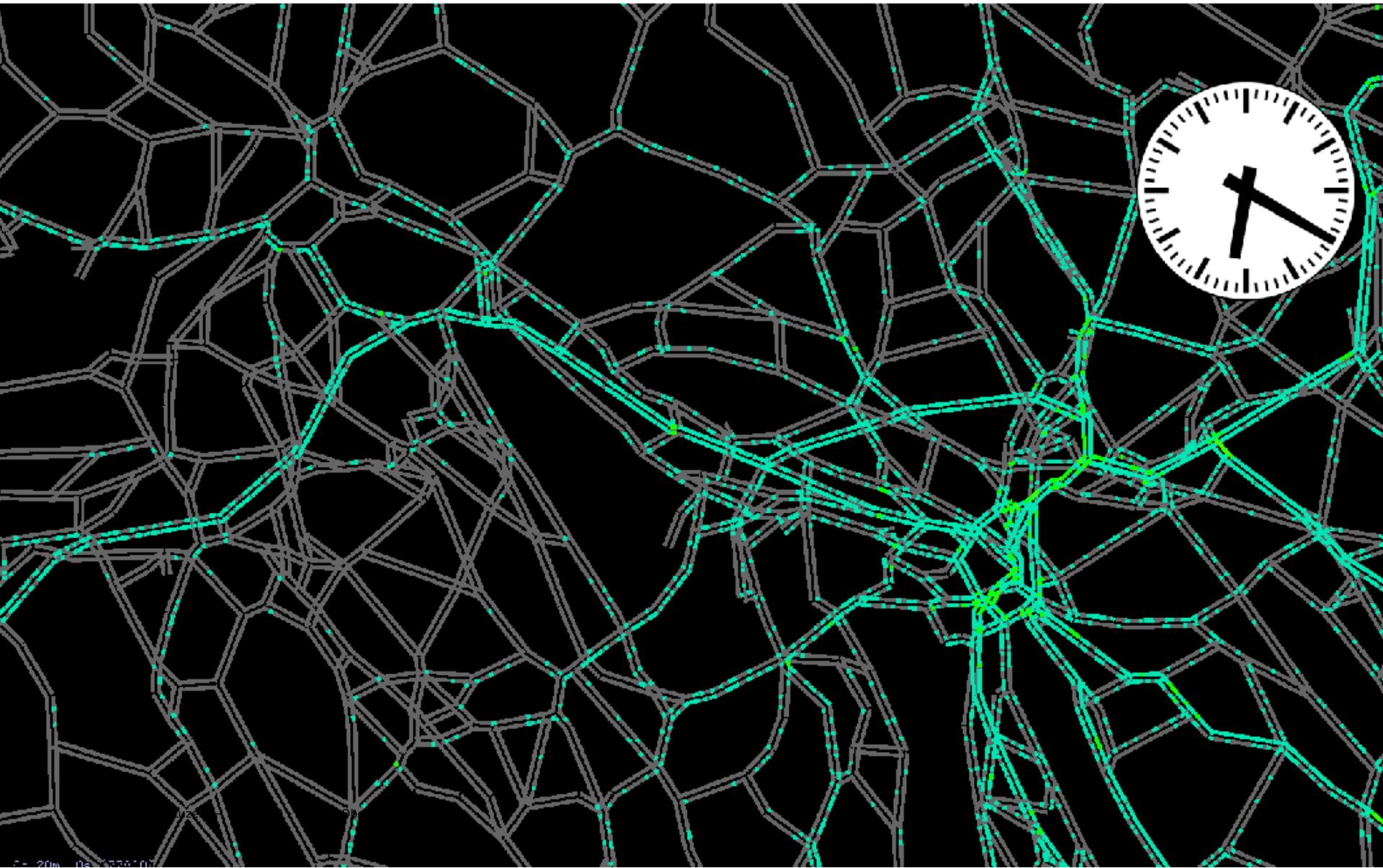
ETH

Eidgenössische Technische Hochschule Zürich
Swiss Federal Institute of Technology Zurich

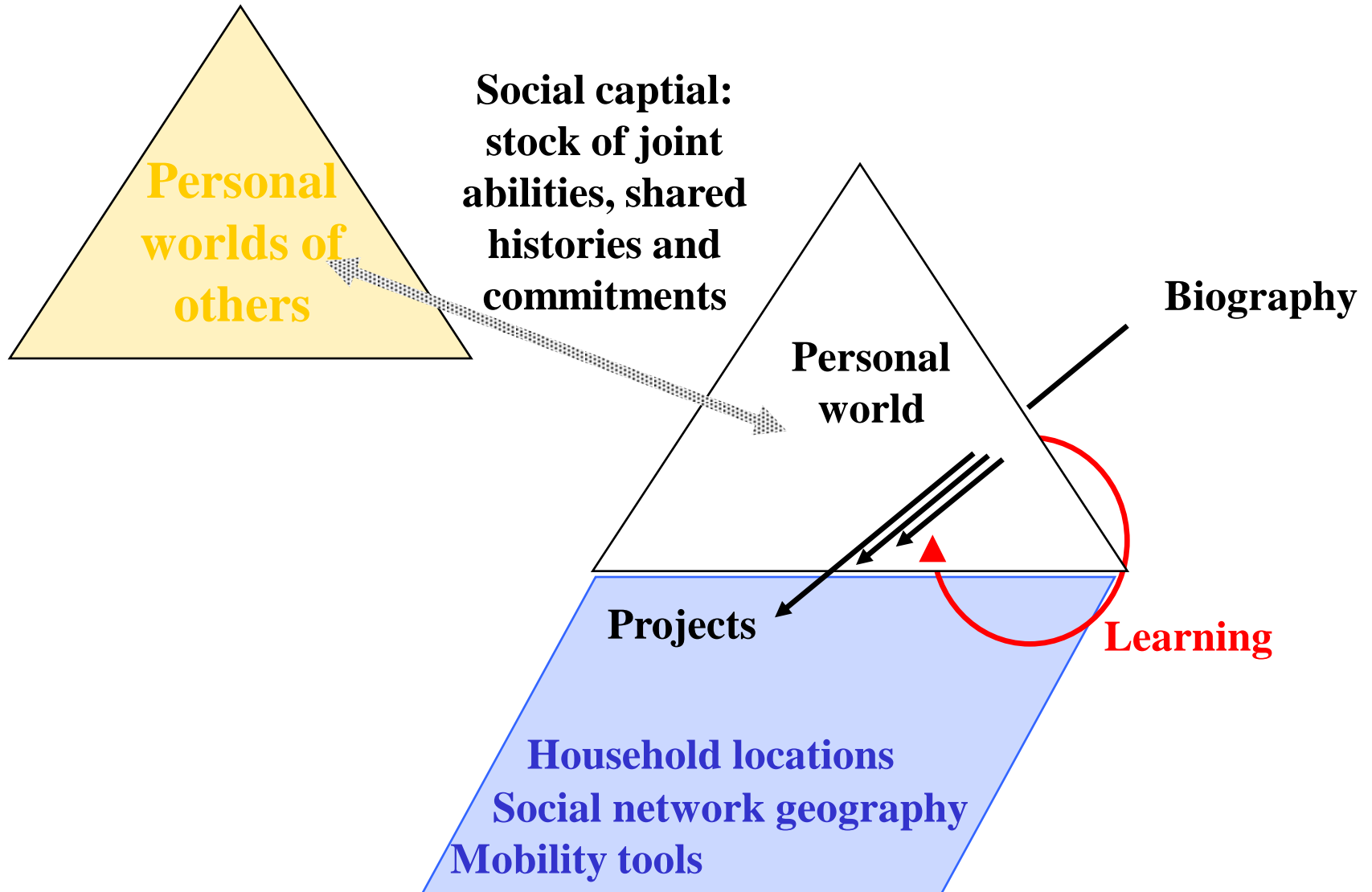
Why transport planning/traffic engineering ?

- Provide forecasts of the changes in use and impact of transport system change (short term to long term)
- Assess the economic viability of those changes (social benefit or individual/firm benefit)
- Provide input into the political assessment of projects and service changes
- Optimise the operation of the systems (social costs)

A peak hour



Conceptual understanding



Time horizons of transport planning

	System	Person
Long term	Slots Regulation	Home/work location Car ownership <i>Social networks</i>
Medium term	Services offered Prices Awareness	Season tickets Projects
Short term	Operation	Daily schedule

Generalized cost function of the schedule

Risk and comfort-adjusted weighted sum of times, expenditures and social content of activities and travel:

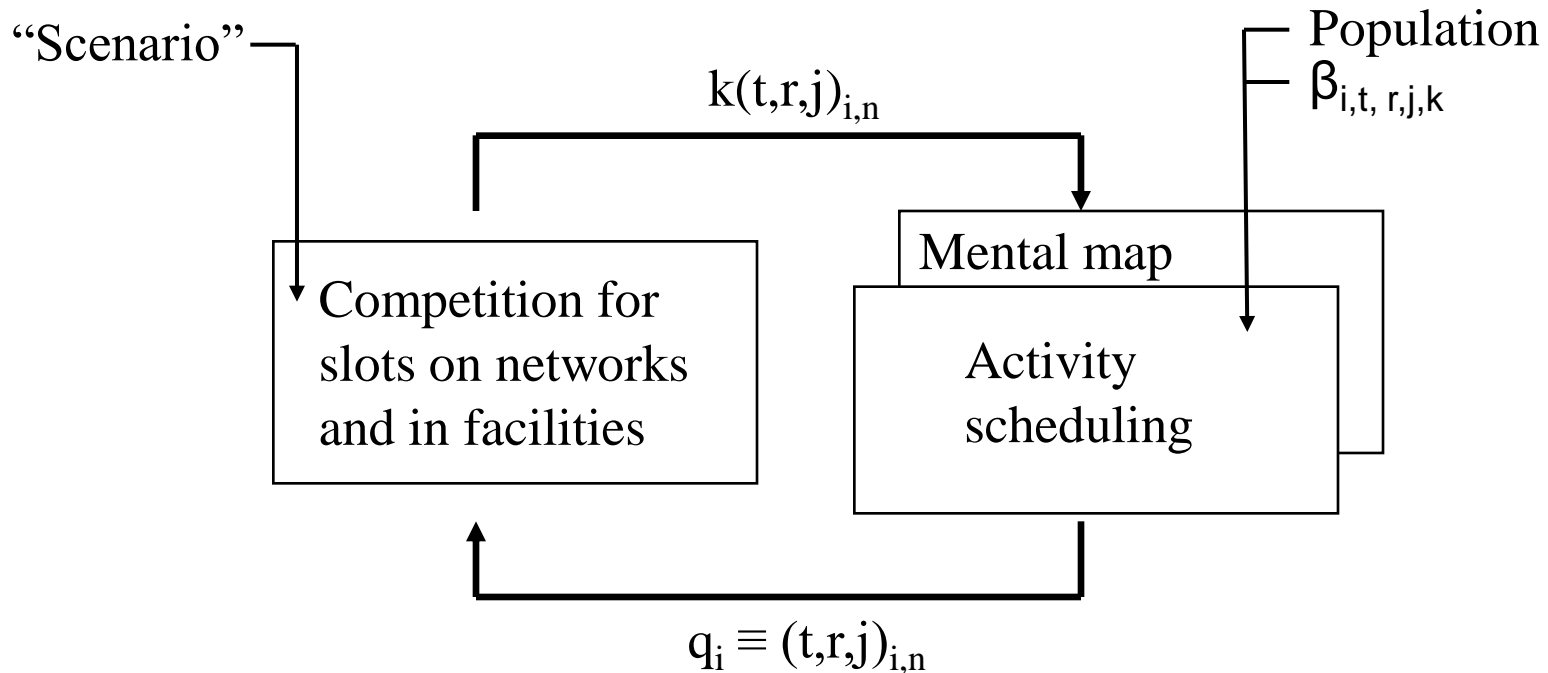
$$U_{plan} = \sum_{i=1}^n U_{act,i} + \sum_{i=2}^n U_{trav,i-1,i}$$

$$U_{act,i} = U_{dur,i} + U_{late.ar,i}$$

Choices currently modelled in MATSim-T

- *Number and type of activities*
- *Sequence of activities*
 - Start and duration of activity
 - Composition of the group undertaking the activity
 - Expenditure division
 - *Location of the activity*
 - Connection between sequential locations
 - Location of access and egress from the mean of transport
 - *Vehicle/means of transport*
 - Route/service
 - Group travelling together
 - Expenditure division

What does MATSim-T do ?



Demand q are the i^{th} movements of person p from the current location at time t on route (connection) r to location j . The resulting generalised costs k are used to adjust the schedules and to change the capacities C and prices P of facilities f

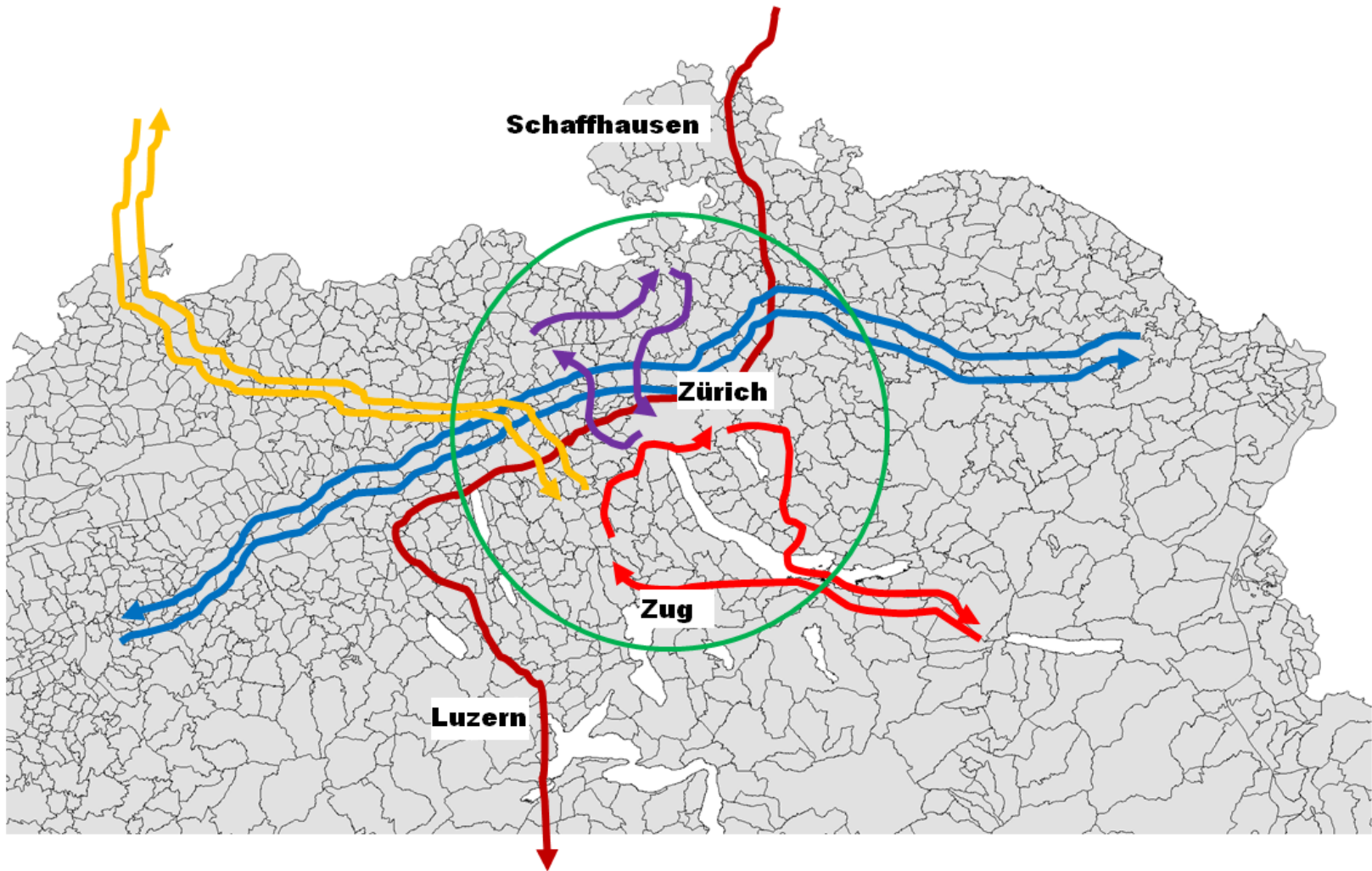
What does it return?

```
<person id="22018">
  <plan score="157.72" selected="yes">
    <act type="h" x="703600" y="236900" link="5757"
                                             end_time="07:35:04" />
    <leg num="0" mode="car" dep_time="07:35:04" trav_time="00:16:31">
      <route>1900 1899 1897</route>
    </leg>
    <act type="w" x="702500" y="236400" link="5749" dur="08:12:05" />
    <leg num="1" mode="car" dep_time="16:03:40" trav_time="01:10:22">
      <route>1899 1848 1925 1924 1923 1922 1068</route>
    </leg>
    <act type="l" x="681450" y="246550" link="2140" dur="01:20:00" />
    <leg num="2" mode="car" dep_time="" trav_time="00:34:35">
      <route>1067 1136 1137 1921 1922 1923 1925 1848 1899</route>
    </leg>
    <act type="h" x="703600" y="236900" link="5757" />
  </plan>
</person>
```

MATSIM-T: Steady-state version

- Scale:
 - 7.5 mio agents,
 - 2 mio homes
 - 1 mio facilities
 - 1 mio links and nodes
- Continuous time resolution: Seconds
- Spatial resolution: Address (individual facilities)

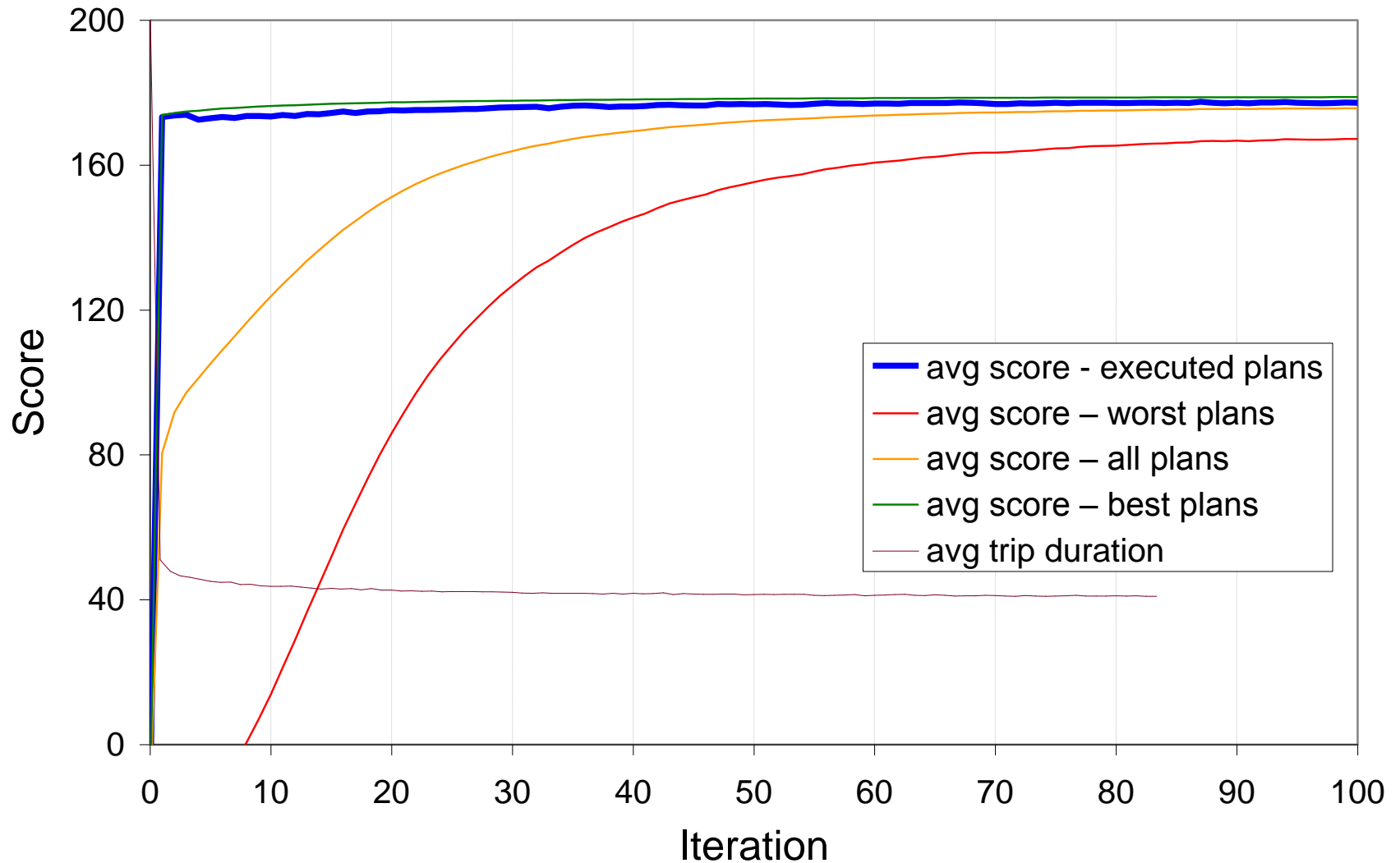
Example: 3% of Swiss population



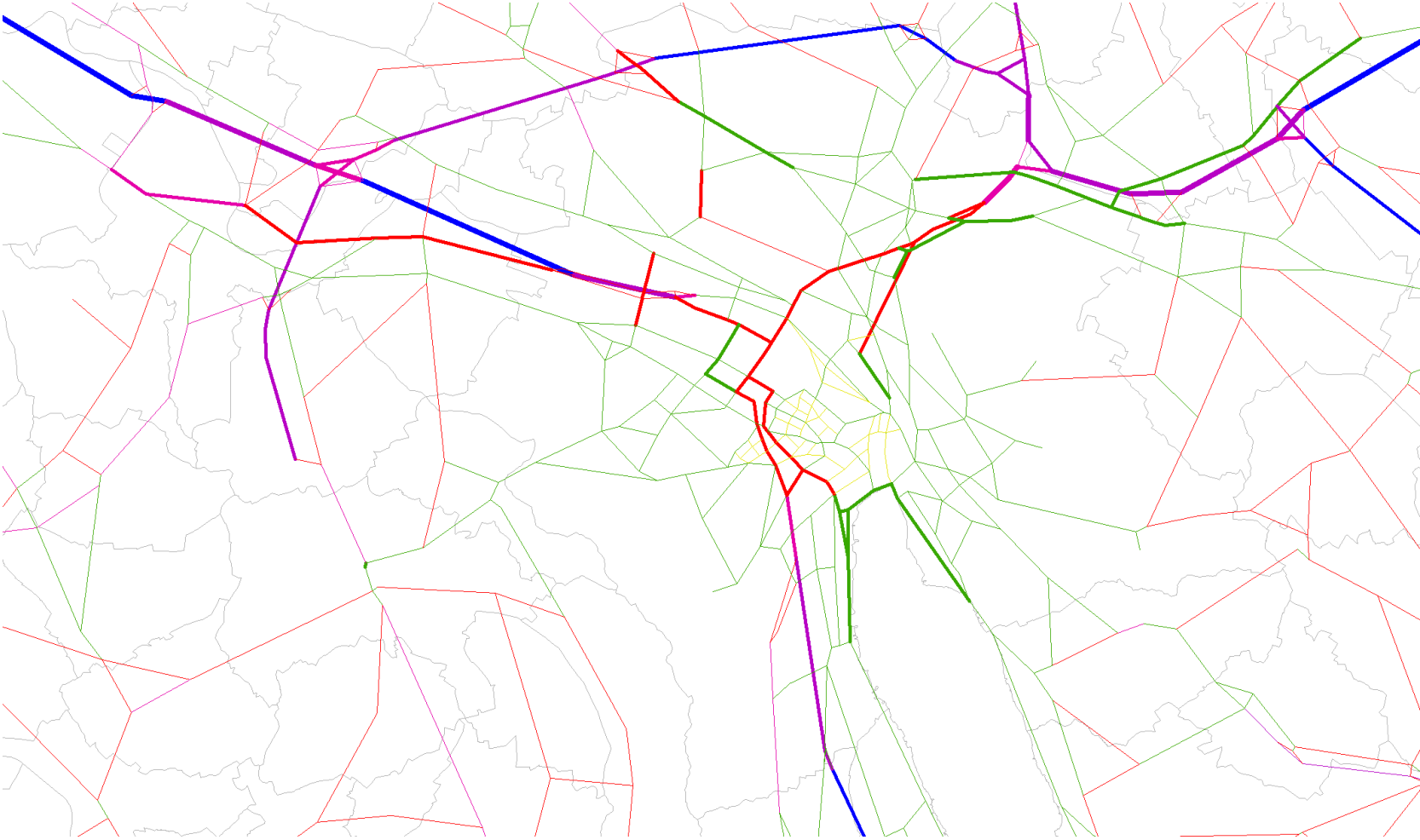
Example: Computing times by step

Operation	Unit	Units/sec
Initial demand		0.12h
Scheduling (fixed components)		14.40h
Scheduling (planomat)	Agent	100
Scheduling (routing)	Agent	1000
Time-step based traffic flow simulation	Agent	300
Learning	Agent	250'000
Total iteration (with I/O)		0.22h
Total run (with I/O) (100 iterations)		23h

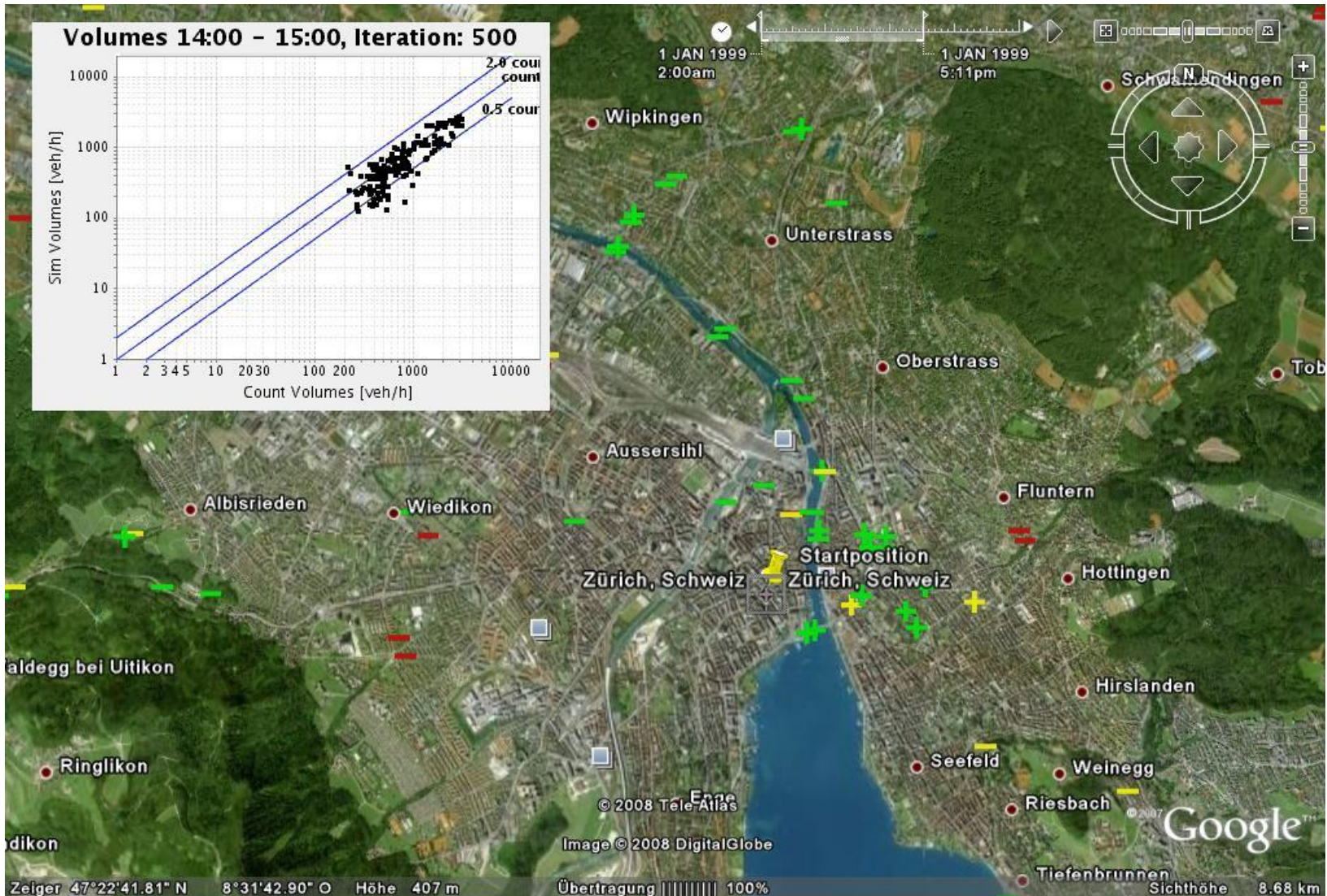
Example: Score/generalised costs by iteration



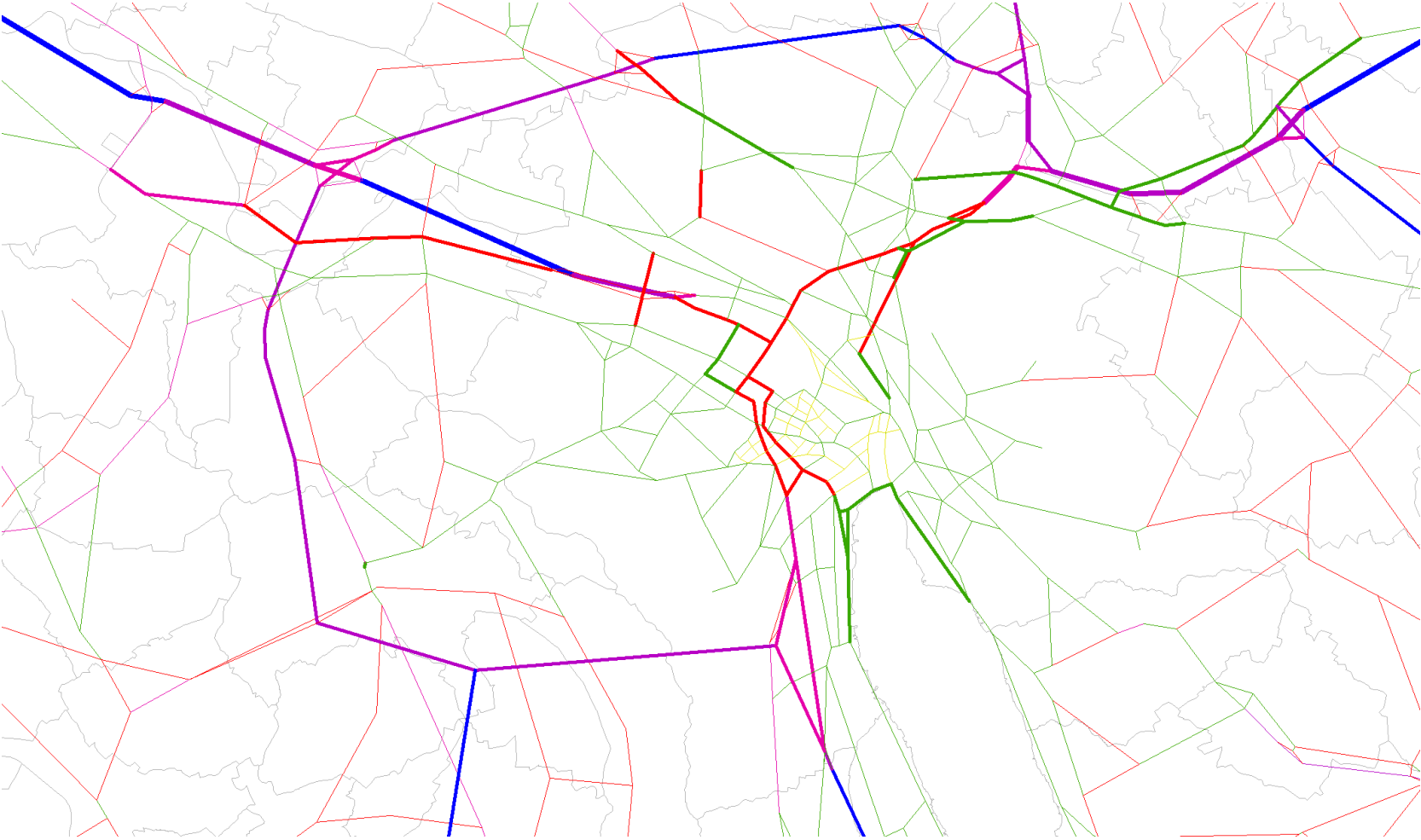
Westumfahrung Zürich: Before



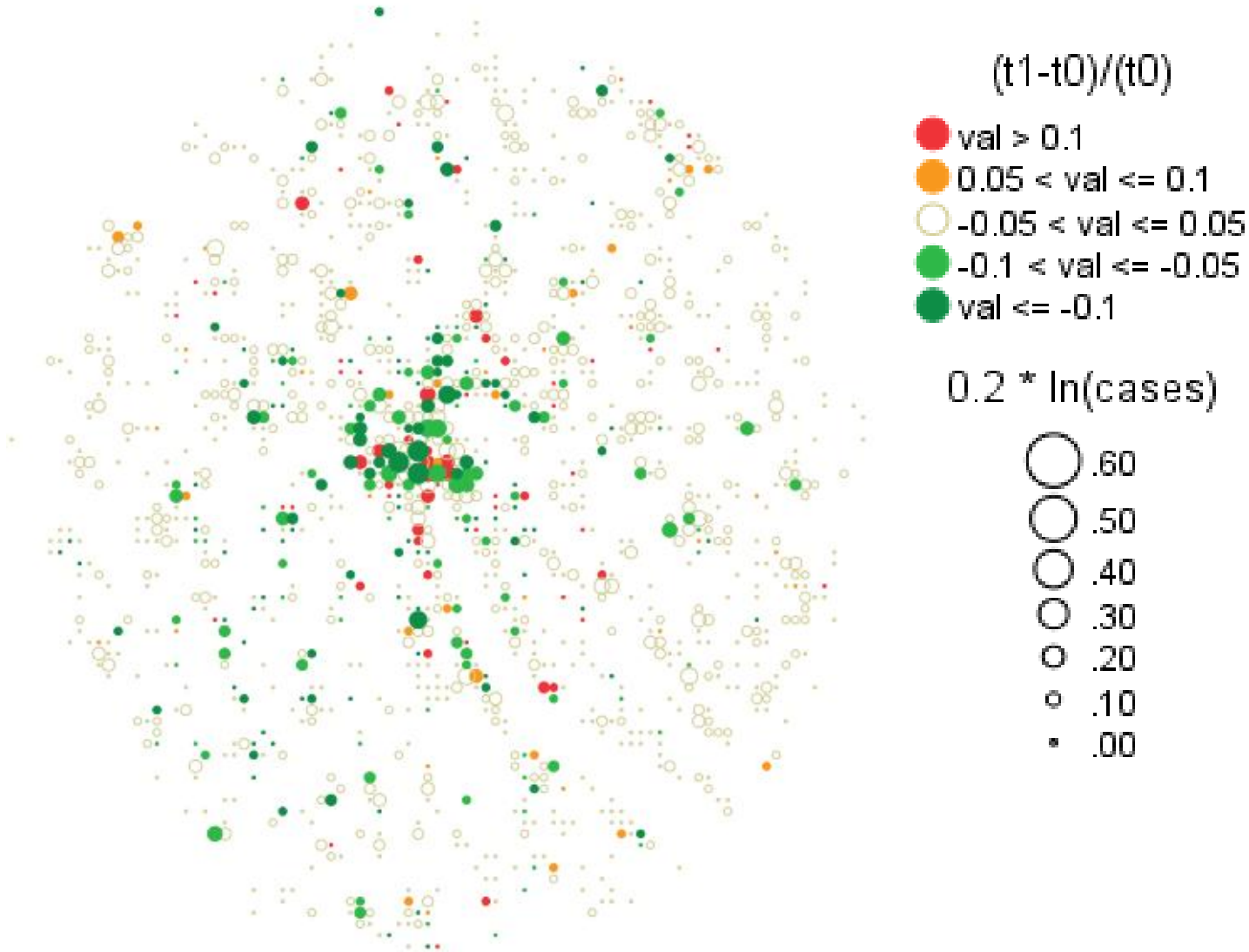
Validation of status-quo



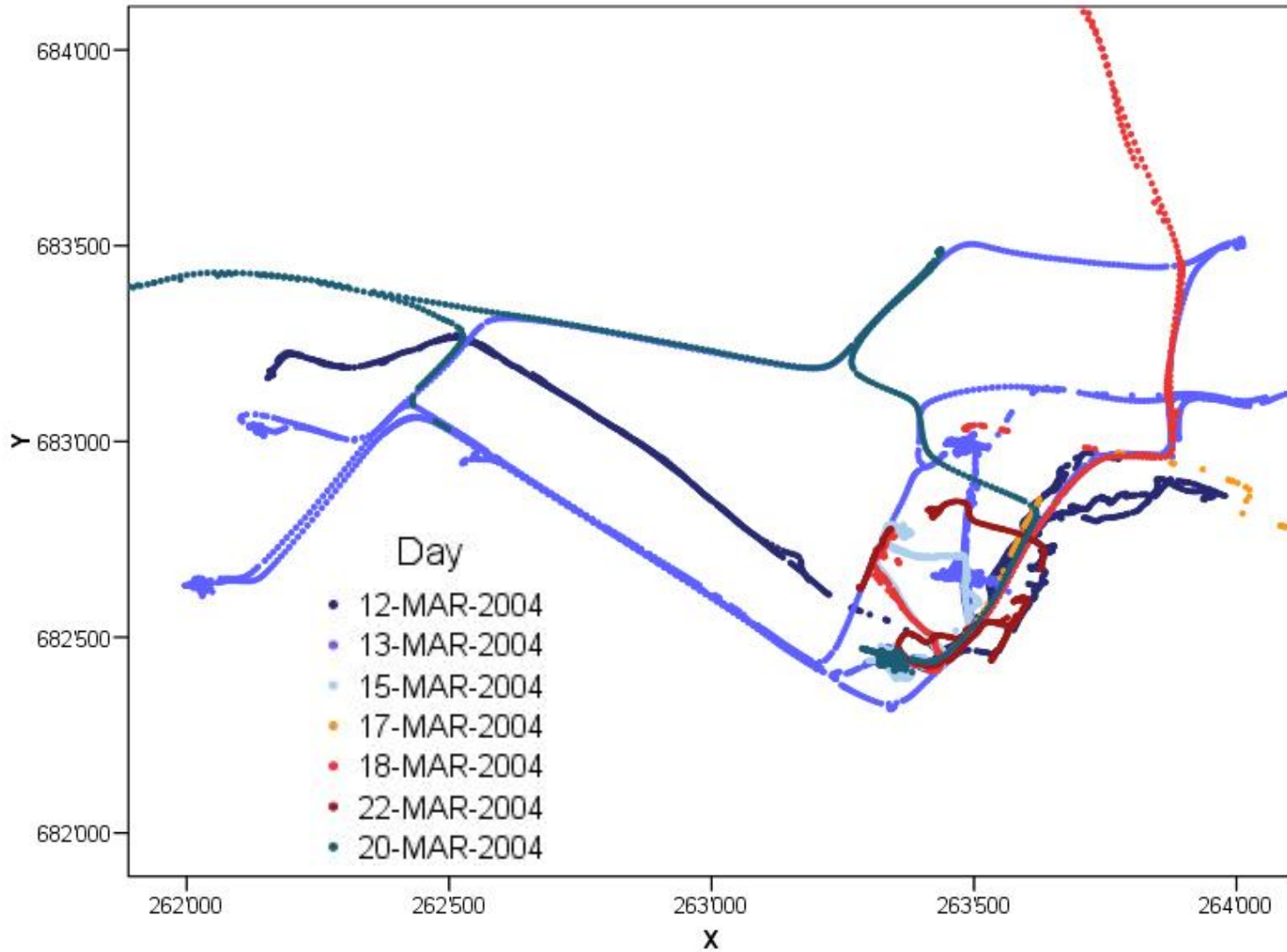
Westumfahrung Zürich: After



Westumfahrung Zürich: Winners/Loosers

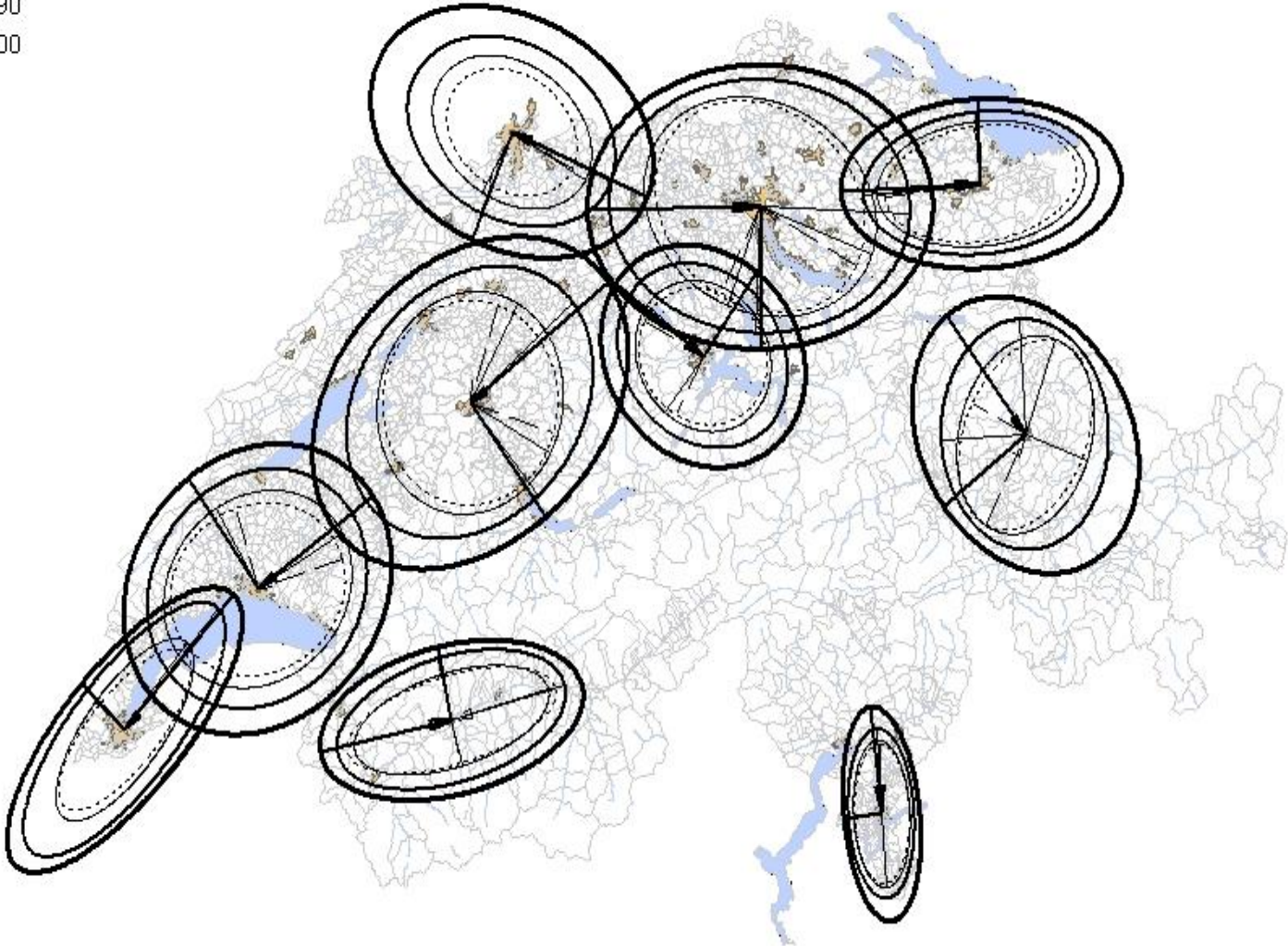


Outlook: Exploit the existing (coming) data wealth

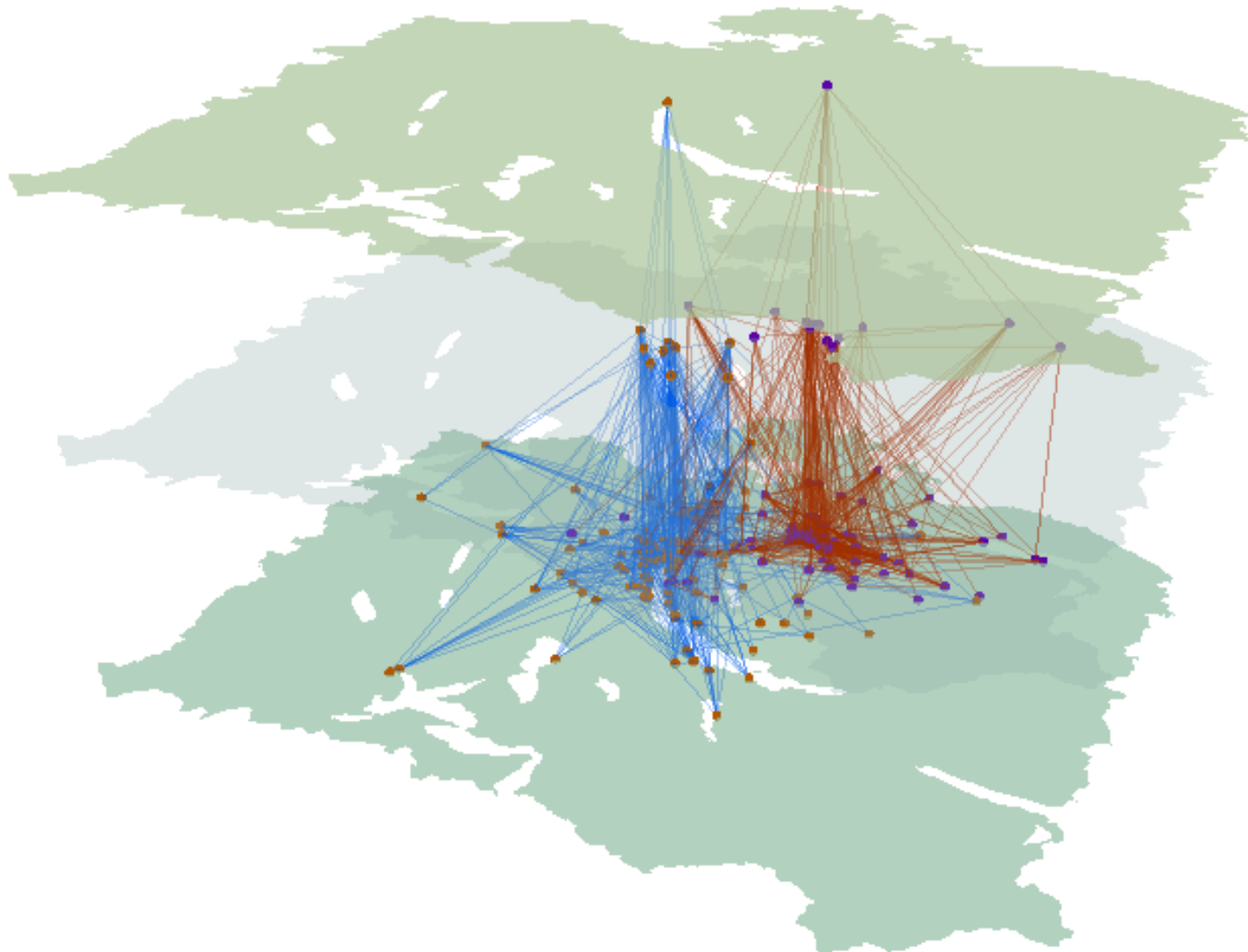


Outlook: Integration of supply side actors

- 1970
- 1980
- 1990
- 2000



Outlook: Joint choice and information flow



Outlook

- Stability of simulation with multiple actor types
- Path dependence
- Development of crisis

- Validation
- Computing times

Kay Axhausen, ETH

Michael Balmer, ETH

David Charypar, ETH

Yu Chen, TU Berlin

Francesco Ciari, ETH

Matthias Feil, ETH

Dominik Grether, TU Berlin

Jeremy Hackney, ETH

Andreas Horni, ETH

Johannes Illenberger, TU Berlin

Gregor Lämmel, TU Berlin

Fabrice Marchal, CRNS/LET

Konrad Meister, ETH

Kai Nagel, TU Berlin

Andreas Neumann, TU Berlin

Marcel Rieser, TU Berlin

Nadine Schüssler, ETH

David Strippgen, TU Berlin

Rashid Waraish, ETH

Christoph Zöllig, ETH